Convex Consensus with Asynchronous Fallback

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Why Convex Consensus?

(Almost) everything is convex if you believe!



n parties



n parties











n parties





n parties with inputs x_1, \ldots, x_n





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Q: What does *meaningful* **mean?**





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river

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A convexity space C on a ground set X



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- \mathbb{R}^D with straight-line convexity \rightarrow Honest-Range Validity (D = 1)
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A geometric invariant

The Helly number

Ζ.

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A: depends on *network model*.

Pb.: How can we even specify t? ω

(A)synchrony

3

And the best-of-both-worlds







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Network-agnostic model: Given $t_a \leq t_s$:

Tolerate t_s corruptions if the network is synchronous.



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- Tolerate *t_s* corruptions if the network is synchronous.
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- Tolerate t_s corruptions if the network is synchronous.
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- (Question here: what pairs (t_s, t_a) are possible?)

Results

Tight results for all 3 models!





Synchronous model:





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Synchronous model: $t < \frac{n}{r}$ Imp Pos Asynchronous model: $t < \frac{n}{\omega+1}$ Pos **Network-agnostic model:** $\max(\omega t_s, \omega t_a + t_s, 2t_s + t_a) < n$ Pos Imp1 Imp2 Imp3 100 $-n = \omega \cdot t_a + t_s$ $-n = 2 \cdot t_s + t_a$ Asynchronous threshold t_a 80 60 40200 2040 60 80 1000 Synchronous threshold t_s (b) $\omega = 3$



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Example for \mathbb{R}^2 :

















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General convexity spaces C:

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- Bad instance guaranteed by def. of ω .
- Previously known: \mathbb{R}^{D} and convex geometries.



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B) Parties *locally* and *deterministically* compute a **valid** output by taking the "*safe area*" (**Agreement** is for free).























































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Generally: a values in the common view, $\leq b$ corrupted

Safe area: intersection of convex hulls of subsets of size a - b*Any* point in safe area is valid, select one *deterministically*.

Safe Area (cont'd)
Who are *a* and **b**?



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A: We intersect **many** *convex sets*, but it suffices to show any ω intersect; Pigeonhole Principle;

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 \Rightarrow at most k of these values are corrupted.

The network is asynchronous?

 \Rightarrow at most t_a of these values are corrupted.

We don't know which?

 $\Rightarrow \mathbf{b} = \max(k, t_a)$

Q: Why is the safe area non-empty?

A: We intersect many *convex sets*, but it suffices to show any ω intersect; Pigeonhole Principle; $\max(\omega t_s, \omega t_a + t_s) < n$



Outlook

5.

And shameless self-advertising







.





















Approximate Agreement?



Approximate Agreement?

Other adversaries?

Hope you enjoyed!





Hope you enjoyed!













No.

Bordón