

Unravelling Expressive Delegations: Complexity and Normative Analysis

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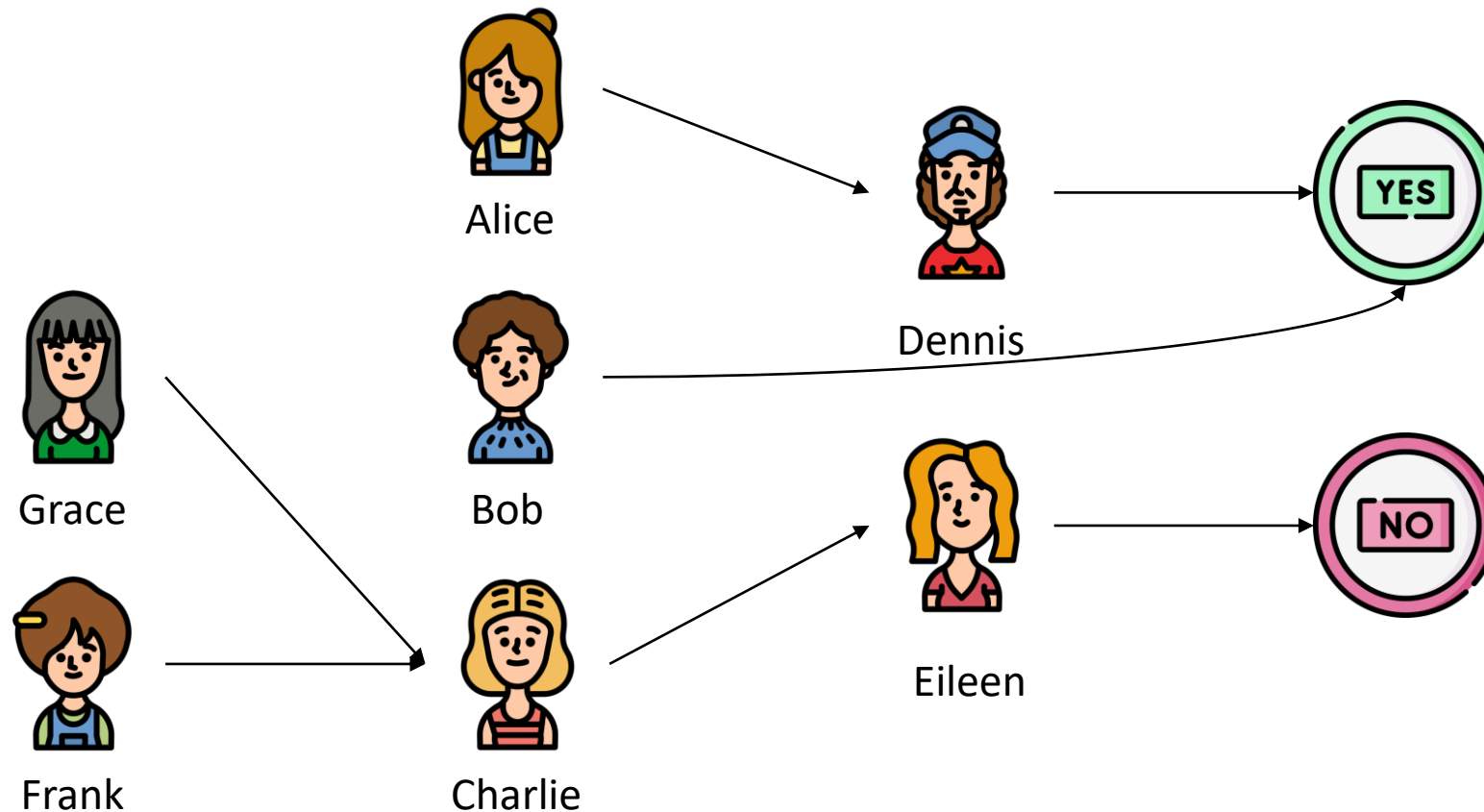
EDITH ELKIND

Summary

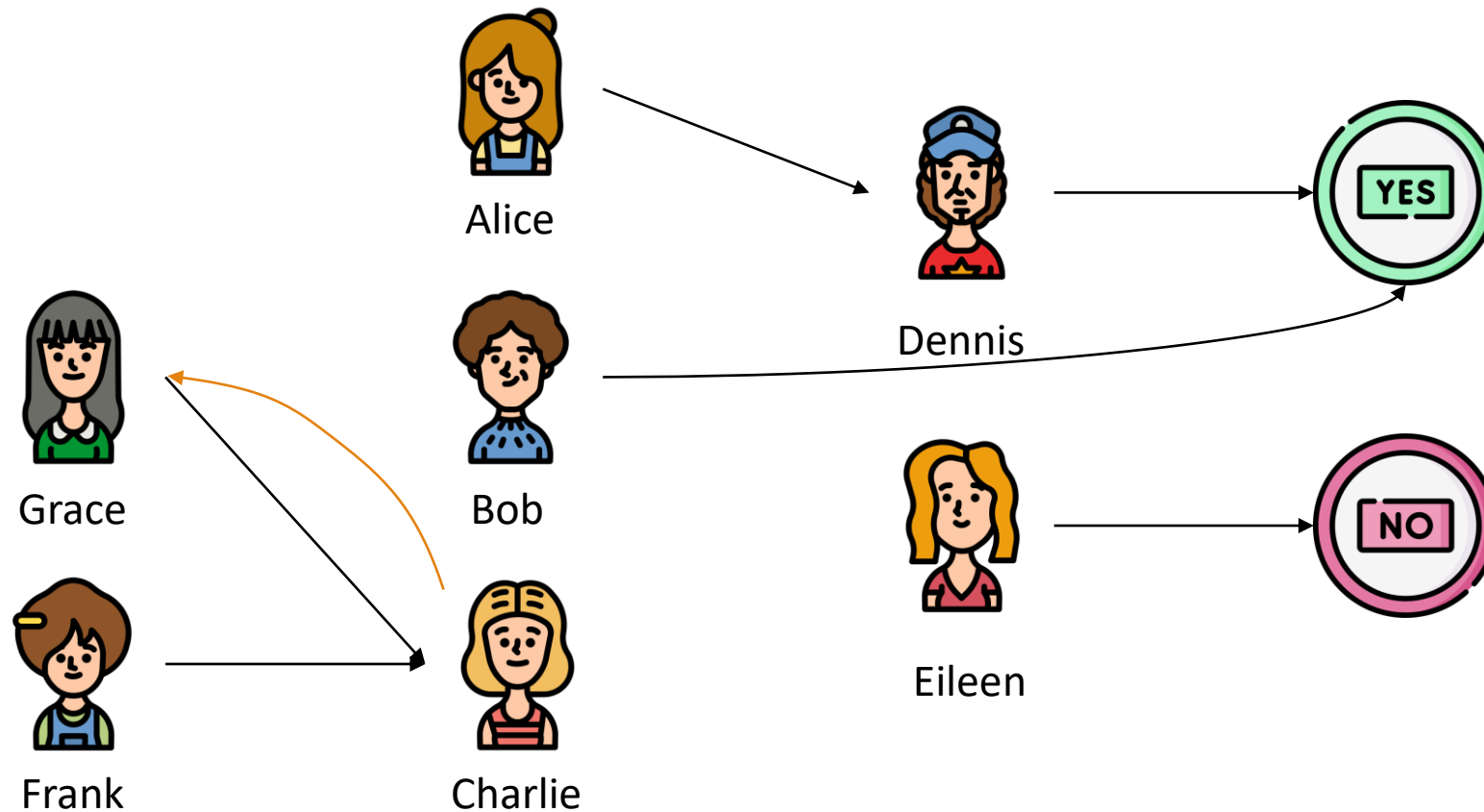
- We consider a **rich model** of Liquid Democracy.
- We prove computational **hardness** for many problems in the rich model.
- We focus on the **simpler model** and prove normative and computational results.

Liquid democracy

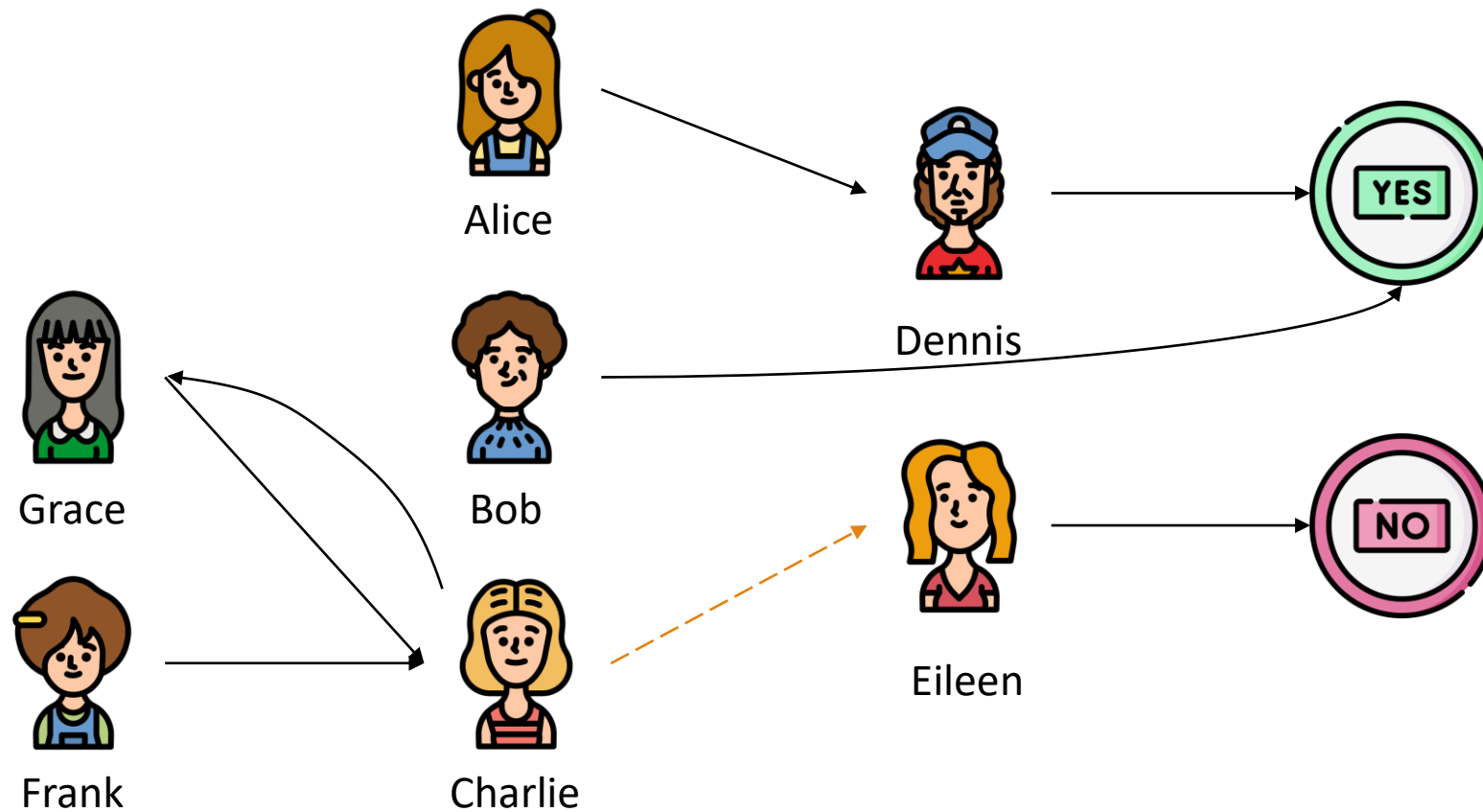
Liquid democracy allows delegations to be **transitive**.



How to deal with cycles?



Solution: ranked delegations



Summary of Liquid Democracy

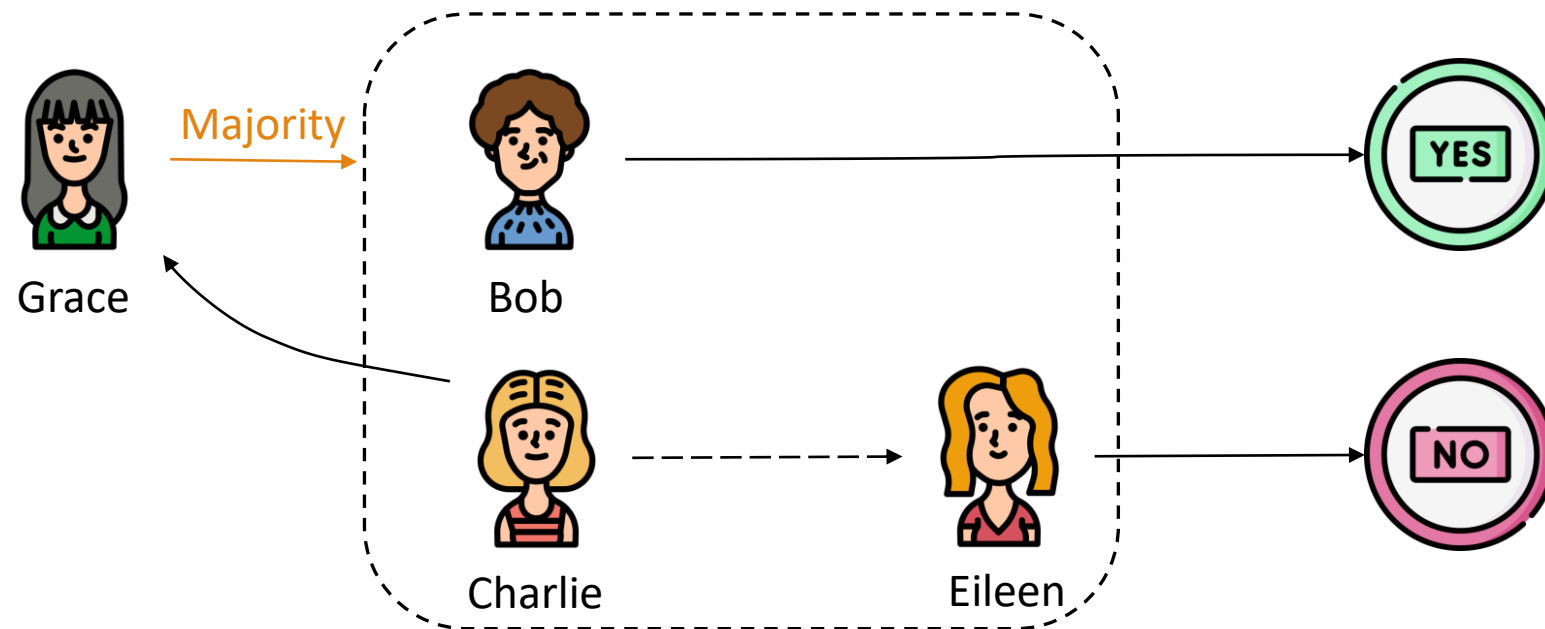
In this model of **Liquid Democracy**:

1. All voters can vote **directly** on issues.
2. Voters can delegate their votes to each other with **transitive delegations**.

Voters submit a **ranked preference order** of delegations. The **final preference** of each delegate must be for either YES or NO, to guarantee that cycles can be resolved.

Smart voting by Colley et al. adds more expressive delegations: voters can delegate to functions of other voters.

Expressive delegation



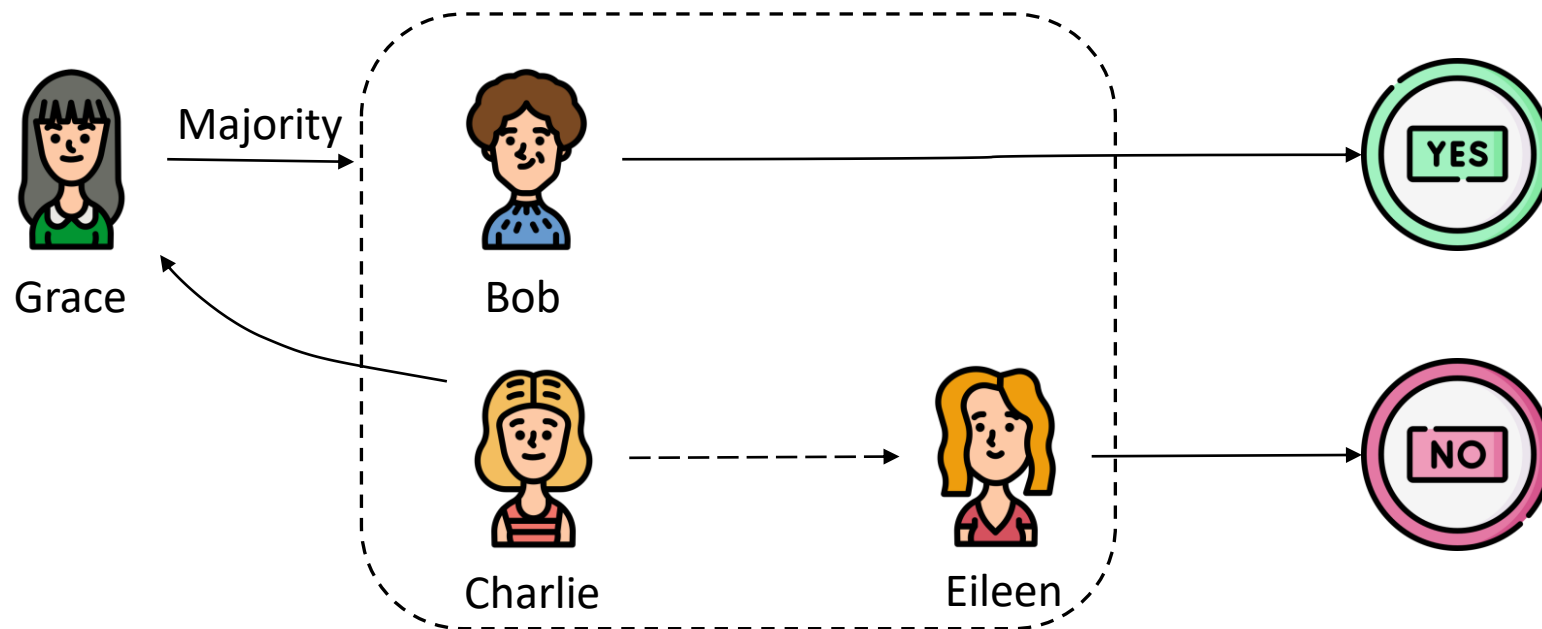
Example ballot

$$B_B = (\text{Yes})$$

$$B_E = (\text{No})$$

$$B_C = (G > E > \text{Yes})$$

$$B_G = (\text{Maj}(B, C, E) > \text{Yes})$$



Converting ballots to votes

Given a ballot for the Smart Voting model, how can we convert it to votes for each agent?

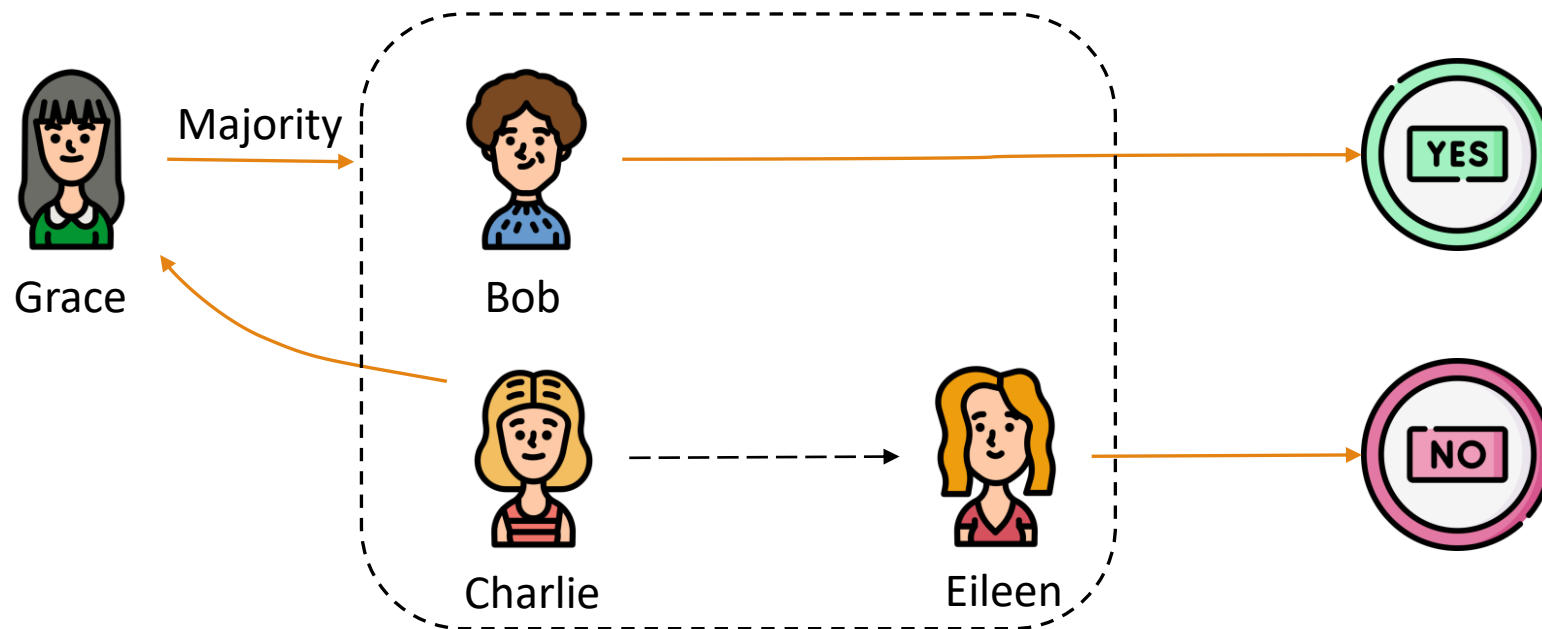
First preferences lead to cycles

$$B_B = (\mathbf{Yes})$$

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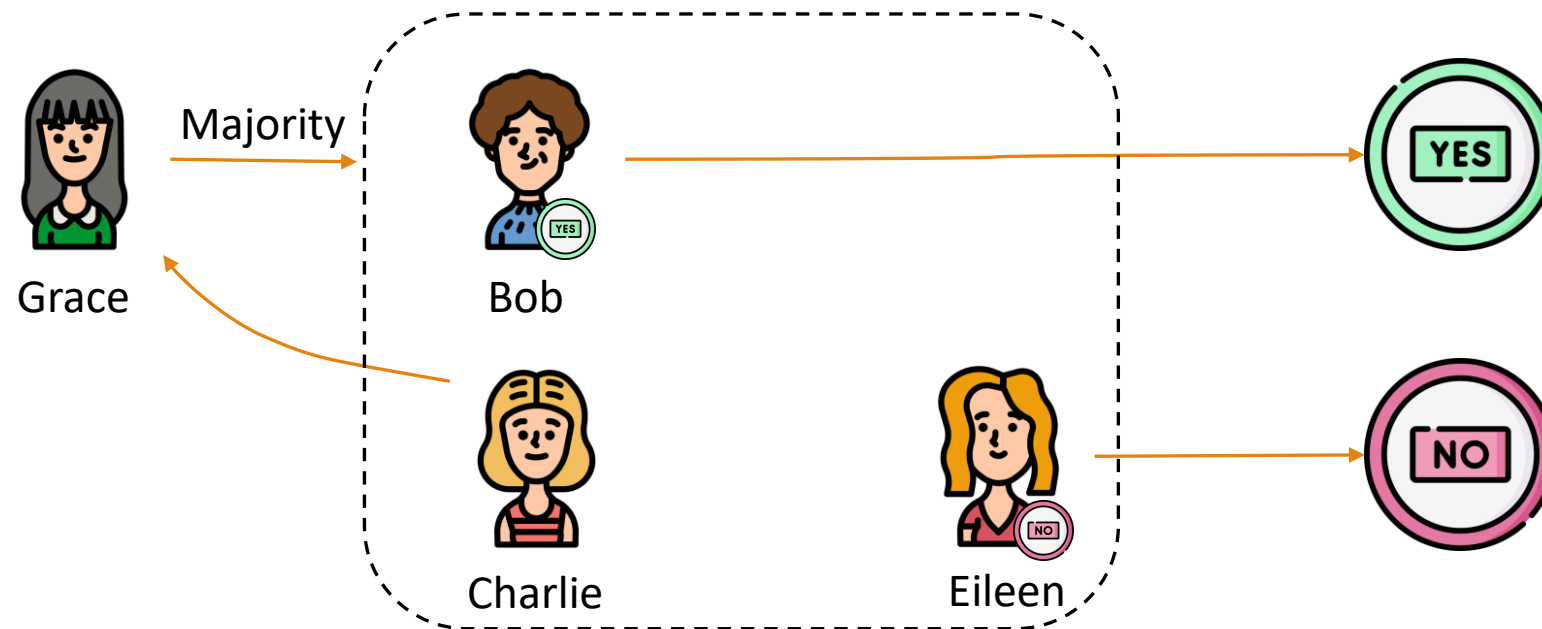
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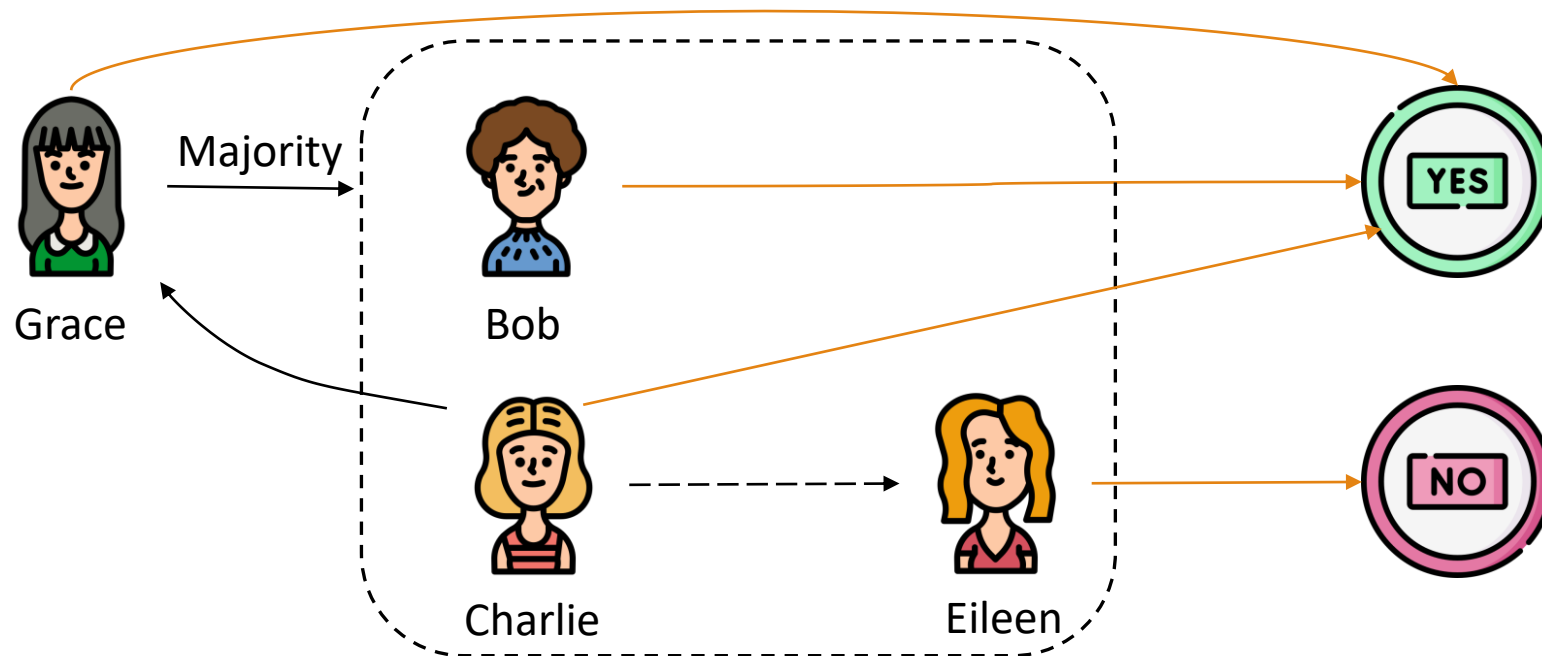
Last preferences are always consistent

$$B_B = (\text{Yes})$$

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Last preferences are always consistent

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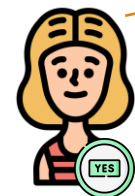
$$B_G = (\text{Maj}(B, C, E) > \text{Yes})$$



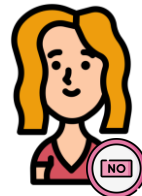
Grace



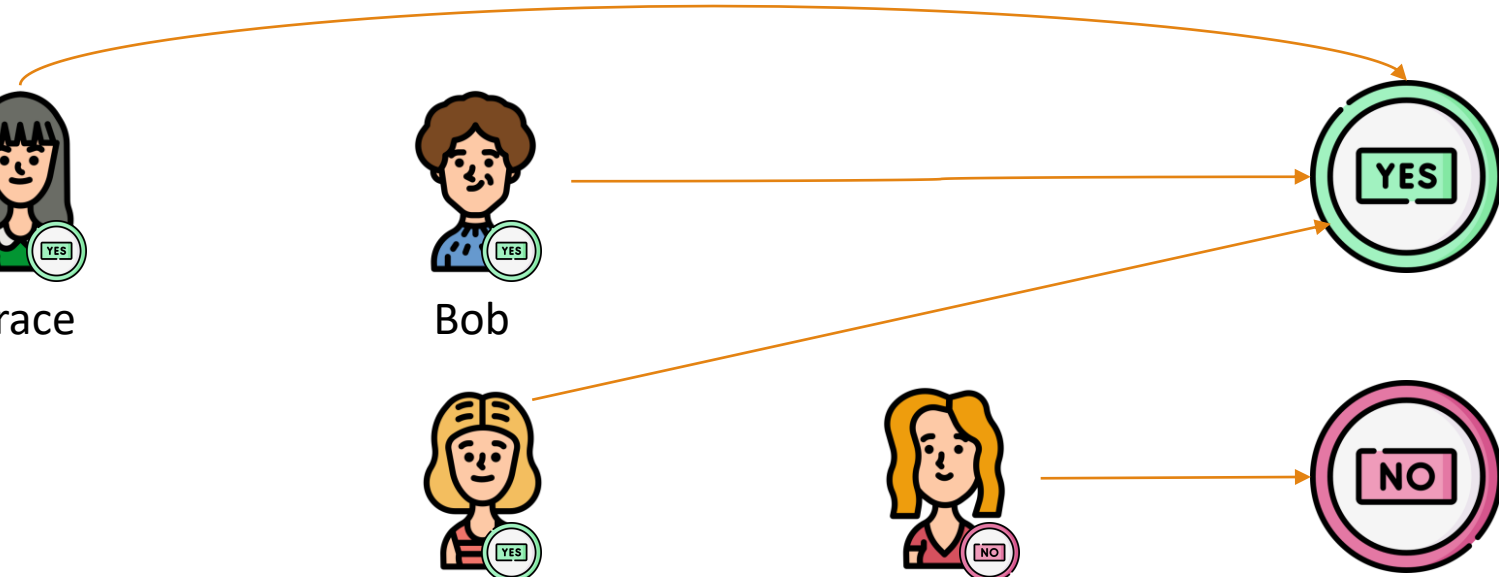
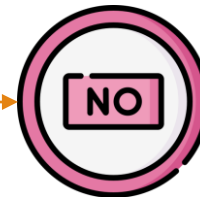
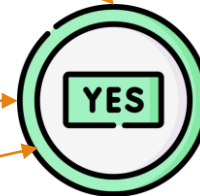
Bob



Charlie



Eileen



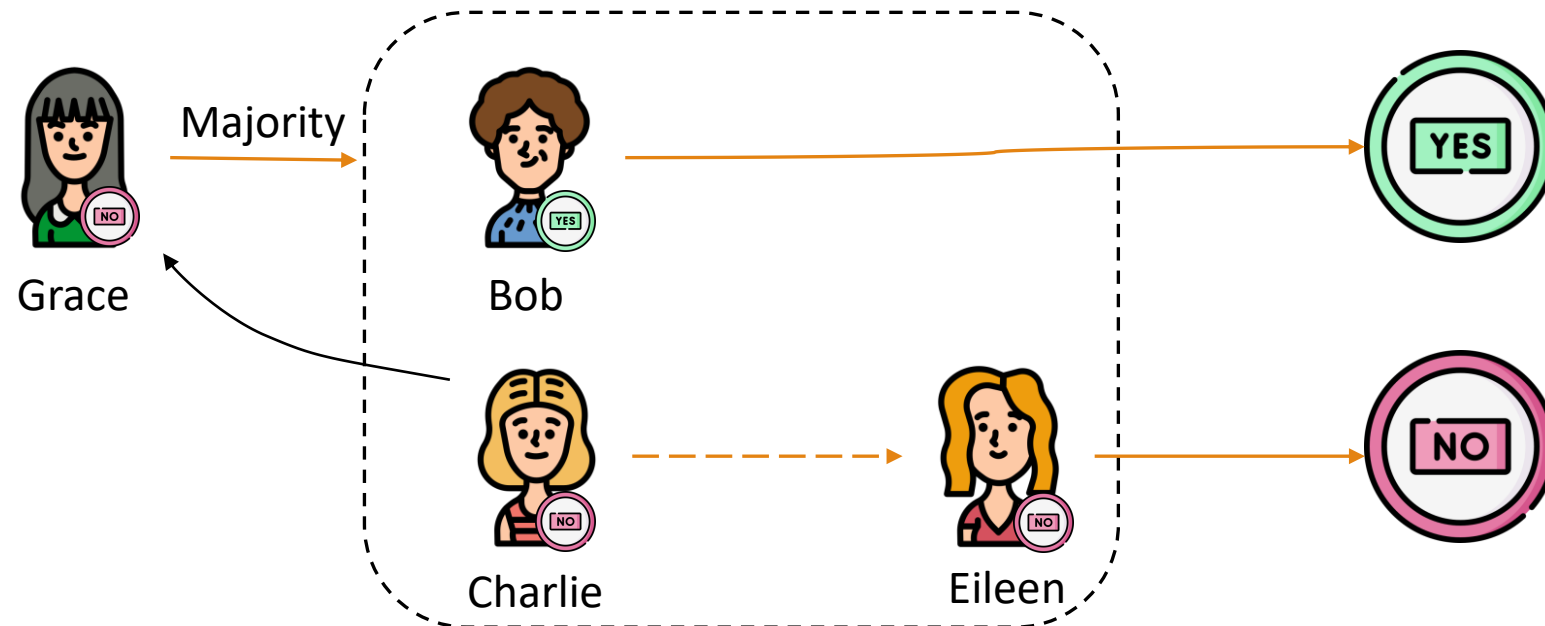
Better consistent certificate

$$B_B = (\mathbf{Yes})$$

$$B_E = (\mathbf{No})$$

$$B_C = (G > \mathbf{E} > \mathbf{Yes})$$

$$B_G = (\mathbf{Maj}(B, C, E) > \mathbf{Yes})$$



The problem

There are a lot of valid preference assignments. How can we pick the “best”?

Colley et al. introduce two notions of “**best**”:

- **MinMax**: Minimise the maximum preference level used
- **MinSum**: Minimise the sum of preference levels used

Are there **efficient** algorithms to compute these?

It turns out that the complexity of the problem depends on what **functions** agents can delegate to.






Results in Colley et al.

LIQUID: Agents can only delegate to a single other agent

\vee : *Binary* Boolean OR

\wedge : *Binary* Boolean AND

Bool: all Boolean functions

	<i>LIQUID</i>	<i>LIQUID</i> \cup $\{\vee\}$ or <i>LIQUID</i> \cup $\{\wedge\}$	<i>LIQUID</i> \cup $\{\wedge_{k=1}^n\}$	<i>LIQUID</i> \cup $\{\vee, \wedge\}$	Monotone $f \notin \{\vee^n, \wedge^n, id\}$ <i>LIQUID</i> \cup $\{f\}$	<i>Bool</i>
MINMAX		?	?	?	?	
MINSUM		?		?	?	

Our results













LIQUID: Agents can only delegate to a single other agent

\vee : *Binary* Boolean OR

\wedge : *Binary* Boolean AND

Bool: all Boolean functions

This is a **complete computational dichotomy** for monotone functions

	<i>LIQUID</i>	<i>LIQUID</i> \cup $\{\vee\}$ or <i>LIQUID</i> \cup $\{\wedge\}$	<i>LIQUID</i> \cup $\{\wedge_{k=1}^n\}$	<i>LIQUID</i> \cup $\{\vee, \wedge\}$	Monotone $f \notin \{\vee^n, \wedge^n, id\}$ <i>LIQUID</i> \cup $\{f\}$	<i>Bool</i>
MINMAX						
MINSUM						

Robustness of hardness

Our hardness results are **robust**.

When we identify hardness for a class of functions \mathcal{F} then:

$\text{MinSum}_{\mathcal{F}}$ is NP-hard even if agents are only allowed **one** non-constant delegation.

$\text{MinMax}_{\mathcal{F}}$ is NP-hard even if agents are only allowed **two** non-constant delegations.

A constant factor **approximation** of either problem is NP-hard.

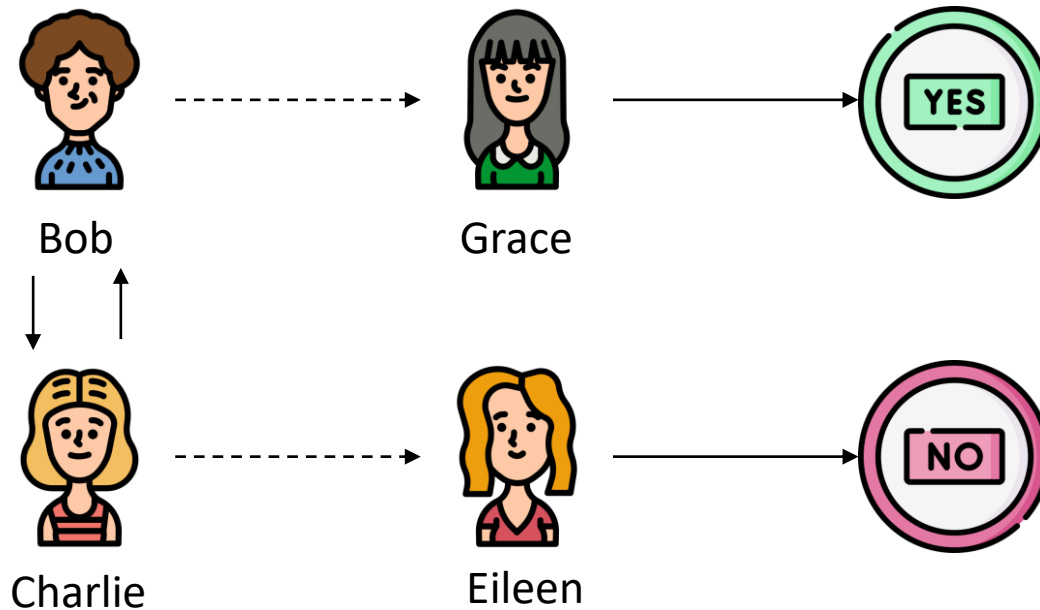
Focusing on the simpler model

Given this hardness, let's focus on the **simpler** model.

In the simple setting, we can **efficiently** compute a MinSum and a MinMax outcome.

However, there are **multiple** such outcomes. How should we pick one?

Example of tied outcome



Grace always votes for **YES**

Eileen always votes for **NO**

Bob and **Charlie** can vote in some outcomes for **YES** and in some outcomes for **NO**

Structure of MinSum outcomes

There exists a **MinSum** outcome \mathbf{c}_{YES} such that if voter v votes for YES in a MinSum outcome they also vote for YES in \mathbf{c}_{YES} .

Similarly, there exists a \mathbf{c}_{NO} .

The same result holds for **MinMax**.

The outcomes \mathbf{c}_{YES} and \mathbf{c}_{NO} can be found in **polynomial time**.

	v_1	v_2	v_3	v_4	v_5
\mathbf{c}_{YES}	1	1	0	1	1
\mathbf{c}_1	1	0	0	1	1
\mathbf{c}_2	0	1	0	1	1
\mathbf{c}_3	1	0	0	1	0
\mathbf{c}_{NO}	0	0	0	1	0

Biased tie-breaking

So, we introduce new **resolute** rules for **MinMax** and **MinSum** that break ties in favour of a given alternative.

This tie-breaking can be used when there's a **default** option. For example, when voting to change the status quo.

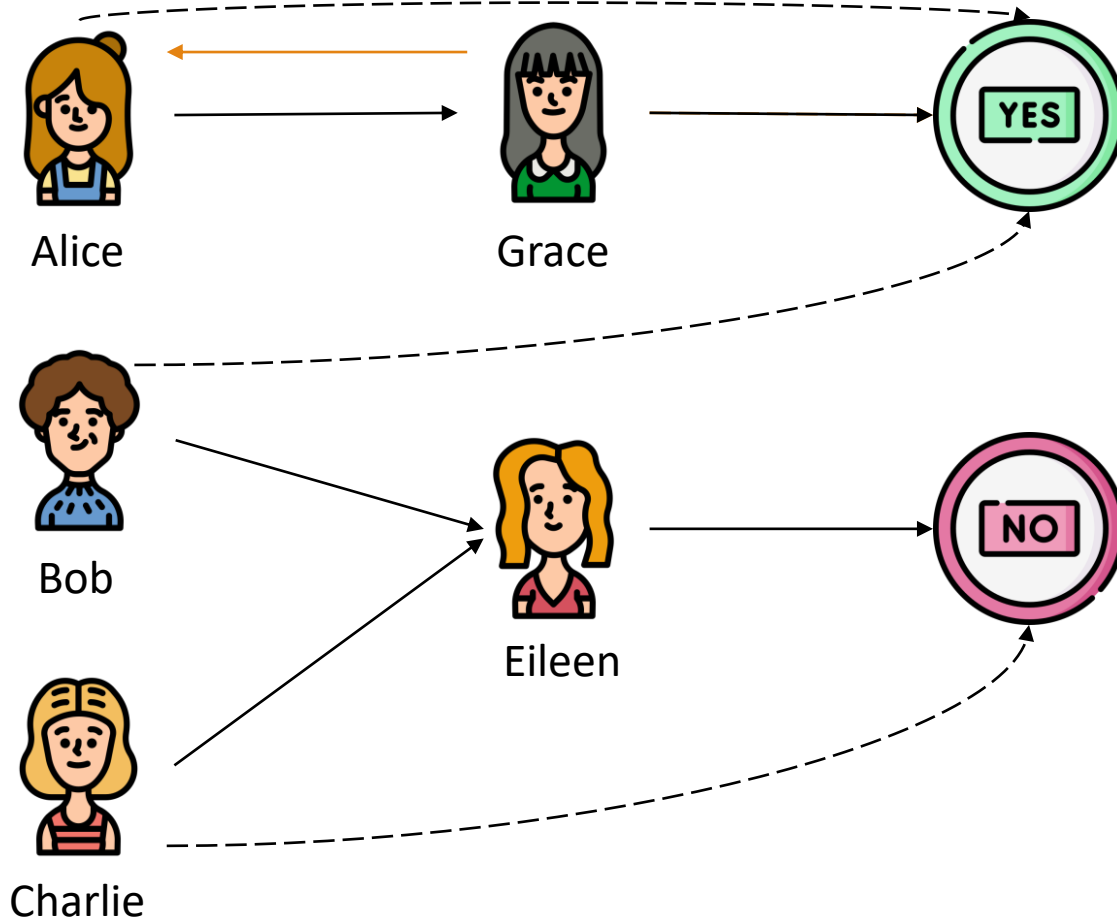
Cast-monotonicity

We introduce a new axiom named **cast-monotonicity**.

It captures the intuition that if agents have a preference over **YES** or **NO**, then their best course of action is to always vote for their preferred outcome.

For irresolute rules we consider that agents who prefer **YES** over **NO** also prefer **{YES}** over **{YES, NO}** over **{NO}**.

MinMax does **not** satisfy cast monotonicity



The outcome using only first preferences would result to the majority voting for **NO**. So, the outcome set is **{NO}**.

But Grace is incentivised to introduce a cycle.

If Grace introduces a cycle by voting for Alice, **MinMax** will return all valid outcomes that use at most second preferences. It will also return the outcome where Bob votes for **YES**. Making the outcome set **{YES, NO}**.

Cast-monotonicity

So, **MinMax** does not satisfy *cast-monotonicity*.

MinSum and the resolute variants with **biased tie-breaking** satisfy *cast-monotonicity*.

Summary

We prove a **characterisation result** for the complexity of monotone functions for MinSum and MinMax.

We propose **resolute** and efficiently computable rules for **biased tie-breaking**.

We introduce *cast-monotonicity* and prove **MinSum** satisfies it, but **MinMax** does not.

References

Icons were taken from Flaticon

The model we consider was proposed by Colley et al. in:

Colley, Rachael, Umberto Grandi, and Arianna Novaro. "Unravelling multi-agent ranked delegations." *Autonomous Agents and Multi-Agent Systems* 36.1 (2022): 9.